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This book provides insights into research in the field of artificial intelligence in combination with robotics technologies. The integration of artificial intelligence and robotic technologies is a highly topical area for researchers and developers from academia and industry around the globe, and it is likely that artificial intelligence will become the main approach for the next generation of robotics research. The tremendous number of artificial intelligence algorithms and big data solutions has significantly extended the range of potential applications for robotic technologies, and has also brought new challenges for the artificial intelligence community. Sharing recent advances in the field, the book features papers by young researchers presented at the 4th International Symposium on Artificial Intelligence and Robotics 2019 (ISAIR2019), held in Daegu, Korea, on August 20-24, 2019.

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Containing 88 papers, the emphasis of this volume is on the control of advanced robots. These robots may be self-contained or part of a system. The applications of such robots vary from manufacturing, assembly and material handling to space work and rescue operations. Topics presented at the Symposium included sensors and robot vision systems as well as the planning and control of robot actions. Main topics covered include the design of control systems and their implementation; advanced sensors and multisensor systems; explicit robot programming; implicit (task-orientated) robot programming; interaction between programming and control systems; simulation as a programming aid; AI techniques for advanced robot systems and autonomous robots.

This book provides state-of-the-art scientific and engineering research findings and developments in the area of mobile robotics and associated support technologies. The book contains peer reviewed articles presented at the CLAWAR 2010 conference. Robots are no longer confined to industrial manufacturing environments. A great deal of interest is invested in the use of robots outside the factory environment. The CLAWAR conference series, established as a high profile international event, acts as a platform for dissemination of research and development findings and supports such a trend to address the current interest in mobile robotics to meet the needs of mankind in various sectors of the society. These include personal care, public health, and services in the domestic, public and industrial environments. The editors of the book have extensive research experience and publications in the area of robotics in general and in mobile robotics specifically, and their experience is reflected in editing the contents of the book.

The three volume set LNCS 4491/4492/4493 constitutes the refereed proceedings of the 4th International Symposium on Neural Networks, ISNN 2007, held in Nanjing, China in June 2007. The 262 revised long papers and 192 revised short papers presented were carefully reviewed and selected from a total of 1.975 submissions. The papers are organized in topical sections on neural fuzzy control, neural networks for control applications, adaptive dynamic programming and reinforcement learning, neural networks for nonlinear systems modeling, robotics, stability analysis of neural networks, learning and approximation, data mining and feature extraction, chaos and synchronization, neural fuzzy systems, training and learning algorithms for neural networks, neural network structures, neural networks for pattern recognition, SOMs, ICA/PCA, biomedical applications, feedforward neural networks, recurrent neural networks, neural networks for optimization, support vector machines, fault diagnosis/detection, communications and signal processing, image/video processing, and applications of neural networks.

The CISM-IFTtoMM RoManSy Symposia have played a dynamic role in the development of the theory and practice of robotics. The proceedings of the eleven symposia to date present a world view of the state of the art. The proceedings of this eleventh edition focus mainly on problems of mechanical engineering and control.

The three volume set LNCS 4232, LNCS 4233, and LNCS 4234 constitutes the refereed proceedings of the 13th International Conference on Neural Information Processing, ICONIP 2006, held in Hong Kong, China in October 2006. The 386 revised full papers presented were carefully reviewed and selected from 1175 submissions.

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